
A Three-Scale Finite Element Method for Elliptic Equations with Rapidly Oscillating Periodic Coefficients

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1 Introduction

On several real world problems the scale ϵ is so smaller than Ω that even with very heavy computer efforts it is impossible to take $h < \epsilon$, h being the scale (mesh-size) of the discrete method used to approximate the solution of

$$L_\epsilon u_\epsilon = -\frac{\partial}{\partial x_i}(a_{ij}(x/\epsilon))\frac{\partial}{\partial x_j}u_\epsilon = f \text{ in } \Omega, \quad u_\epsilon = 0 \text{ on } \partial\Omega. \quad (1)$$

where the matrix $a(y) = (a_{ij}(y))$ is symmetric positive definite, whose entries are periodic functions of y with periodic cell Y . More specifically we assume $a_{ij} \in C^{1,\beta}(\mathbb{R}^2)$, $\beta > 0$. It is also assumed that there exists positive constants γ_a and β_a such that $\gamma_a\|\xi\|^2 \leq a_{ij}(y)\xi_i\xi_j \leq \beta_a\|\xi\|^2$ for all $\xi \in \mathbb{R}^2$ and $y \in \bar{Y}$. Recently new numerical methods have been proposed for approximating the solution u_ϵ with meshes sizes $h > \epsilon$ (or $h \gg \epsilon$) but capturing the oscillations presented by the the solution u_ϵ ; see for example [HW97,EHW00,SM02,EE03,S03,AB04,]. In [VS05a] we developed a numerical scheme for this problem for the case the domain Ω is rectangular, and quasi-optimal error rate estimates were obtained. That method, opposed to the methods [HW97,EHW00,S03] is strongly based on asymptotic expansions of u_ϵ . We construct a first order asymptotic expansion for u_ϵ , and then we numerically approximate each term separately.

In this paper, we modify the method in [VS05a] for the case where Ω is a convex polygonal regional with rational normals. In this case, a better treatment for the normal derivative of u_0 is required. We propose an approximation based on hybrid finite element for the flux and we obtain optimal error rate estimates for the L_2 norm and H^1 broken semi-norm.

2 Notation

We assume that $Y = [0, 1] \times [0, 1]$ and Ω is bounded convex polygonal region in \mathfrak{R}^2 , whose boundary $\partial\Omega = \cup \Gamma^k$, $k = 1, \dots, m$ where each Γ^k is a line segment with minimal outward normal denoted by $N_k = (p_k, q_k)^t$, where p_k and q_k are integers and relative primes. This hypothesis is required to guarantee periodicity of $a(x/\epsilon)$ on Γ_k [MV97].

Let $D \subset \mathfrak{R}^2$ be an open set. We use the standard notation $\|\cdot\|_{s,D}$, $\|\cdot\|_{s,p,D}$ for $H^s(D)$ and $W_p^s(D)$ norms, $|\cdot|_{s,D}$, $|\cdot|_{s,p,D}$ their semi-norms. and $\|\cdot\|_{s,h,D}$ for the broken norms related to a regular partition $\mathcal{T}_h(D) = K_1, K_2, \dots, K_m$ of D . Throughout this paper, when we do not make reference to the domain D it is assumed that $D = \Omega$. It is continually used the Einstein summation convention, i.e. repeated indices indicate summation, except when the indice k is used. In what follows c denotes a generic constant independent of ϵ , h , and functions being evaluated.

3 Theoretical Approximation

3.1 The Asymptotic Expansion

The solution u_ϵ can be approximated by an asymptotic expansion. This approximation can be found using equation (1) and the ansatz

$$u_\epsilon(x) = u_0(x, x/\epsilon) + \epsilon u_1(x, x/\epsilon) + \epsilon^2 u_2(x, x/\epsilon) + \dots,$$

where the functions $u_j(x, y)$ are Y periodic in y . These terms are defined below; for more details see [BLP80, OSY92, MV97].

Let χ^j be the Y periodic solution with zero average on Y of

$$\nabla_y \cdot a(y) \nabla_y \chi^j = \nabla_y \cdot a(y) \nabla_y y_j = \frac{\partial}{\partial y_i} a_{ij}(y). \quad (2)$$

We have that $\chi^j \in C^{2,\beta}(\mathfrak{R}^2)$ when $a_{ij} \in C^{1,\beta}(\mathfrak{R}^2)$. Define the matrix:

$$A_{ij} = \frac{1}{|Y|} \int_Y a_{lm}(y) \frac{\partial}{\partial y_l} (y_i - \chi^i) \frac{\partial}{\partial y_m} (y_j - \chi^j) dy. \quad (3)$$

It is easy to see that the matrix A is symmetric positive definite. Define $u_0 \in H^2(\Omega) \cap H_0^1(\Omega)$ as the solution of

$$-\nabla \cdot A \nabla u_0 = f \quad \text{in } \Omega, \quad u_0 = 0 \quad \text{on } \partial\Omega, \quad (4)$$

and let $u_1(x, \frac{x}{\epsilon}) = -\chi^j(\frac{x}{\epsilon}) \frac{\partial u_0}{\partial x_j}(x)$. Note that $u_0 + \epsilon u_1$ does not satisfy the zero Dirichlet boundary condition on $\partial\Omega$. In order to correct this, the boundary corrector term $\theta_\epsilon \in H^1(\Omega)$ is introduced as the solution of

$$-\nabla \cdot a(x/\epsilon) \nabla \theta_\epsilon = 0 \quad \text{in } \Omega, \quad \theta_\epsilon = -u_1(x, \frac{x}{\epsilon}) \quad \text{on } \partial\Omega. \quad (5)$$

Therefore we obtain $u_0 + \epsilon u_1 + \epsilon \theta_\epsilon \in H_0^1(\Omega)$.

3.2 Boundary Corrector Approximation

Note that the coefficients $a_{ij}(x/\epsilon)$ and the boundary values $-u_1(x, \frac{x}{\epsilon})$ of the Equation (5) are highly oscillatory, hence it is not a trivial problem to obtain a good discretization for θ_ϵ . We propose an analytical approximation for θ_ϵ , denoted by ϕ_ϵ that satisfies the oscillating boundary condition and is more suitable for numerical approximation.

Note that $u_0 = 0$ along $\partial\Omega$ implies $\nabla u_\epsilon|_{\Gamma_k} = \eta_k \partial_{\eta_k} u_0$. We then decompose $\theta_\epsilon = \tilde{\theta}_\epsilon + \bar{\theta}_\epsilon$ where

$$-\nabla \cdot a(x/\epsilon) \nabla \tilde{\theta}_\epsilon = 0 \text{ in } \Omega, \quad \tilde{\theta}_\epsilon = -u_1 - \chi^* \partial_{\eta_k} u_0 \text{ on } \partial\Omega, \quad (6)$$

and

$$-\nabla \cdot a(x/\epsilon) \nabla \bar{\theta}_\epsilon = 0 \text{ in } \Omega, \quad \bar{\theta}_\epsilon = \chi^* \partial_{\eta_k} u_0 \text{ on } \partial\Omega, \quad (7)$$

where $\chi^*|_{\Gamma_k} = \chi_k^*$ are properly chosen constants. In Remark 1 we show that the problems (6) and (7) are well posed. The approximation ϕ_ϵ for θ_ϵ is defined later as $\tilde{\phi}_\epsilon + \bar{\phi}_\epsilon$, where $\tilde{\phi}_\epsilon \approx \tilde{\theta}_\epsilon$ and $\bar{\phi}_\epsilon \approx \bar{\theta}_\epsilon$.

Next we define constants χ_k^* for which the approximation $\tilde{\phi}_\epsilon$ decays exponentially to zero away from the boundary and is suitable for numerical approximation.

Let $\tau_k = (\eta^k)^\perp$ be the $\pi/2$ rotation counterclockwise of η^k . We introduce the following normal and tangential coordinate system

$$\begin{pmatrix} y'_1 \\ y'_2 \end{pmatrix} = - \begin{pmatrix} \eta^k T y \\ \tau_k T y \end{pmatrix} \quad (8)$$

We observe that a function periodic in y with period 1 is periodic in y' with period $T_k = (p_k^2 + q_k^2)^{1/2}$. Associated to each side Γ_k of $\partial\Omega$, let $G_k = \{y \in \mathbb{R}^2; y'_1 \leq 0; \text{ and } 0 \leq y'_2 \leq T_k\}$; and v_k the solution of

$$\begin{aligned} -\nabla_y \cdot a(y + \delta_\epsilon \eta^k) \nabla_y v_k &= 0 \text{ in } G_k, \\ v_k(y) &= \chi^j (y + \delta_\epsilon \eta^k) \eta_j^k \text{ on } \{y \in G_k, y'_1 = 0\} \\ v_k|_{y'_2=0} &= v_k|_{y'_2=T_k}, \text{ for } -\infty < y'_1 < 0, \\ \text{and } \frac{\partial v_k}{\partial y_i} \exp(-\gamma y'_1) &\in L^2(G_k), \quad i = 1, 2, \end{aligned}$$

where $\delta_\epsilon = T_k (s_k / (\epsilon T_k) - \lfloor s_k / (\epsilon T_k) \rfloor)$, and s_k is such that $\Gamma_k \subset \{x \in \mathbb{R}^2; x \cdot \eta_k = s_k\}$; ($\lfloor \cdot \rfloor$ denotes the integer part).

Let

$$\begin{aligned} \chi_k^* &= \frac{1}{(A\eta^k, \eta^k) T_k} \left(\int_0^{T_k} \left[\chi^l a_{ij} \left(\delta_{jm} - \frac{\partial \chi^m}{\partial y_j} \right) \eta_i^k \eta_m^k \eta_l^k \right] \Big|_{y'_1 = \delta_\epsilon} dy'_2 \right. \\ &\quad \left. + \int_{G_k} (a(y + \delta_\epsilon \eta^k) \nabla_y v_k \cdot \nabla_y v_k) dy \right), \end{aligned}$$

It can be shown [MV97] that v_k decays exponentially to zero for $y'_1 \rightarrow -\infty$, i.e. $(v_k - \chi_k^*) \exp(-\gamma y'_1) \in L^2(G_k)$.

We note by Remark 1 that $(u_1(x, \frac{x}{\epsilon}) - \chi^* \partial_\eta u_0)|_{\Gamma_k} \in H_{00}^{1/2}(\Gamma_k)$. Thus we can split $\tilde{\theta}_\epsilon = \sum_{k \in \{1, \dots, N\}} \tilde{\theta}_\epsilon^k$, where

$$L_\epsilon \tilde{\theta}_\epsilon^k = 0 \text{ in } \Omega, \quad \tilde{\theta}_\epsilon^k = \begin{cases} -u_1(x, \frac{x}{\epsilon}) - \chi^* \partial_\eta u_0 & \text{on } \Gamma_k, \\ 0 & \text{on } \partial\Omega \setminus \Gamma_k. \end{cases}$$

We approximate $\tilde{\theta}_\epsilon^k$ by $\tilde{\phi}_\epsilon^k$ given by

$$\tilde{\phi}_\epsilon^k(x_1, x_2) = \varphi_k(x_1) \left(v_k \left(\frac{x - s_k \eta_k}{\epsilon} \right) - \chi_k^* \right) \nabla u_0 \cdot \eta_k. \quad (9)$$

In order to simplify the definition of the function $\varphi_k(x)$ let us assume $\Gamma_k = \{x \in \mathfrak{R}^2; x_1 = 0, 0 \leq x_2 \leq c\}$ and that x_1^+ is the inner normal direction. Let $\Gamma_{k-1}, \Gamma_{k+1}$ be the edges with vertices at the point $(0, c), (0, 0)$ respectively and let $\alpha_k > 0$ and $\alpha_{k+1} < 0$ be the angles between x_1 axis and Γ_{k-1} and Γ_{k+1} respectively. Then we define

$$\varphi_k(x) = \begin{cases} 1 & \text{if } 0 \leq x_1 \leq \delta; 0 \leq x_2 \leq c \\ 1 - (x_2 - c)/(x_1 \tan \alpha_k) & \text{if } 0 \leq x_1 \leq \delta; x_2 > c \\ 1 + x_2/(x_1 \tan \alpha_{k+1}) & \text{if } 0 \leq x_1 \leq \delta; x_2 < 0 \\ \text{smooth} & \text{if } \delta \leq x_1 \leq 2\delta \\ 0 & \text{if } x_1 \geq 2\delta \end{cases}$$

Hence $\tilde{\phi}_\epsilon = \sum_{k \in \{1, \dots, N\}} \tilde{\phi}_\epsilon^k$ approximate $\tilde{\theta}_\epsilon$, and $\tilde{\phi}_\epsilon = \tilde{\theta}_\epsilon$ on the boundary of Ω .

The boundary condition imposed on Equation (7) does not depend on ϵ . An effective approximation for $\tilde{\theta}_\epsilon$ is given by $\bar{\phi} \in H^1(\Omega)$ the solution of

$$-\nabla \cdot A \nabla \bar{\phi} = 0 \text{ in } \Omega, \quad \bar{\phi} = \chi^* \partial_\eta u_0 \text{ on } \partial\Omega.$$

We define our theoretical approximation for u_ϵ as $u_0 + \epsilon u_1 + \epsilon \phi_\epsilon$, where $\phi_\epsilon = \tilde{\phi}_\epsilon + \bar{\phi}$. Note that $\phi_\epsilon|_{\partial\Omega} = \theta_\epsilon|_{\partial\Omega}$, therefore $u_0 + \epsilon u_1 + \epsilon \phi_\epsilon = 0$ on $\partial\Omega$. In [VS05b] we prove the following error bounds

Theorem 1. *Assume that $a_{ij} \in C^{1,\beta}(\mathfrak{R}^2)$ and $u_0 \in H^2(\Omega)$, ($u_0 \in H^3(\Omega)$). Then there exists a constant c , such that*

$$\begin{aligned} \|u_\epsilon - u_0 - \epsilon u_1 - \epsilon \phi_\epsilon\|_1 &\leq c\epsilon \|u_0\|_2 \\ (\|u_\epsilon - u_0 - \epsilon u_1 - \epsilon \phi_\epsilon\|_0 &\leq \epsilon^{3/2} \|u_0\|_3). \end{aligned}$$

Remark 1. Since u_0 satisfies zero Dirichlet boundary condition on $\partial\Omega$ and $u_0 \in H^2(\Omega)$, we have $\frac{\partial u_0}{\partial \eta^k} \in H_{00}^{1/2}(\Gamma_k)$ and $\|\chi^* \partial_\eta u_0\|_{H^{1/2}(\partial\Omega)} \leq c(\chi^*) \|u_0\|_2$. Note also that $u_1(x, \frac{x}{\epsilon}) = -\chi^j \left(\frac{x}{\epsilon} \right) \frac{\partial u_0}{\partial x_j}(x)$, since $\chi^j \in C^{2,\beta}(\mathfrak{R}^2)$ we get $u_1|_{\Gamma_k} \in H_{00}^{1/2}(\Gamma_k)$.

4 Finite Element Approximation

We now describe how to numerically approximate the terms u_0 , u_1 , $\tilde{\phi}_\epsilon$ and $\bar{\phi}$.

- Solve the cell problem (2) with a second order accurate conforming finite element in a partition $\mathcal{T}_{\hat{h}}(Y)$. Call these solutions $\chi_{\hat{h}}^j$.
- Define $A_{ij}^{\hat{h}} = \frac{1}{|Y|} \int_Y a_{lm}(y) \frac{\partial}{\partial y_l} (y_i - \chi_{\hat{h}}^i) \frac{\partial}{\partial y_m} (y_j - \chi_{\hat{h}}^j) dy$.
- Let $V^h(\Omega)$ be a conforming second order accurate finite element in a mesh $\mathcal{T}_h(\Omega)$, and $V_0^h(\Omega) = V^h(\Omega) \cap H_0^1(\Omega)$. Define $u_0^{h,\hat{h}} \in V_0^h$ the solution of

$$\int_{\Omega} (A^{\hat{h}} \nabla u_0^{h,\hat{h}}, \nabla v^h) dx = \int_{\Omega} f v^h dx, \quad \forall v^h \in V_0^h.$$

- Define $u_1^{h,\hat{h}}$ as $u_1^{h,\hat{h}}(x) = -\chi_{\hat{h}}^j \left(\frac{x}{\epsilon} \right) \frac{\partial u_0^{h,\hat{h}}}{\partial x_j}(x)$. Note that this leads to a non-conforming approximation for u_1 in the partition $\mathcal{T}_h(\Omega)$.
- Define Y_k^h the trace of V^h at Γ_k . And let $\lambda_k^h \in \Gamma_k^h$, $\lambda_k^h = 0$ at $\partial\Gamma_k$ satisfying

$$\int_{\Omega} A_{ij}^{\hat{h}} \partial_i u_0^h \partial_j \phi dx = \int_{\Omega} f \phi dx + \int_{\Gamma_k} \lambda_k^h \phi d\sigma. \quad (10)$$

$\forall \phi \in V^h$; $\phi|_{\partial\Omega \setminus \Gamma_k} = 0$ so approximate $\partial_\eta u_0$ by $\mu^{h,\hat{h}}$ where

$$\mu^{h,\hat{h}}|_{\Gamma_k} = \lambda_k^h / A_{ll}^{\hat{h}}, \quad \begin{cases} l = 1 \text{ if } k = 1, 3. \\ l = 2 \text{ if } k = 2, 4. \end{cases}$$

- Let p be a positive integer and $G_k^p = \{y \in \mathbb{R}^2; y'_1 \leq 0, |y'_1| \leq p; \text{ and } 0 \leq y'_2 \leq T_k\}$. Define $\tilde{v}_k \in H^1(G_k^p)$ the solution of

$$\begin{aligned} -\nabla_y \cdot a(y + \delta_\epsilon \eta^k) \nabla_y \tilde{v}_k &= 0 \text{ in } G_k^p, \\ \tilde{v}_k(y) &= \chi_{\hat{h}}^1(y + \delta_\epsilon \eta^k), \text{ on } \{y \in G_k, y'_1 = 0\}, \\ \partial_\eta \tilde{v}_k &= 0, \text{ on } \{y \in G_k^p; |y'_1| = p\}, \\ \text{and } v_k|_{y'_2=0} &= v_k|_{y'_2=T_k}, \text{ for } |y'_1| < p. \end{aligned}$$

Let $v_k^{\hat{h},p}$ be a numerical approximation of \tilde{v}_k using a second order accurate conforming finite element on a mesh $\mathcal{T}_{\hat{h}}(G_\epsilon^p)$.

- Define

$$\begin{aligned} \chi_k^{*,\hat{h},p} &= \frac{1}{(A^{\hat{h}} \eta^k, \eta^k) T_k} \left(\int_0^{T_k} \left[\chi_{\hat{h}}^l a_{ij} \left(\delta_{jm} - \frac{\partial \chi_{\hat{h}}^m}{\partial y_j} \right) \eta_i^k \eta_m^k \eta_l^k \right] \Big|_{y'_1 = \delta_\epsilon} dy'_2 \right. \\ &\quad \left. + \int_{G_k} (a(y + \delta_\epsilon \eta^k) \nabla_y v_k^{\hat{h},p} \cdot \nabla_y v_k^{\hat{h},p}) dy \right), \end{aligned}$$

- Given $g : \Gamma_k \rightarrow \mathfrak{R}$, let $E_k(g) \in V^h(\Omega)$ be the extension by zero of g to Ω .

- Observe that in Equation. (9) the term $v_k((x - s_k\eta_k)/\epsilon)$ appears. Since the approximation $v_k^{\hat{h},p}$ is defined in G_k^p , we can calculate $v_k^{\hat{h},p}((x - s_k\eta_k)/\epsilon)$ only if $|x'_1 - s_k| \leq \epsilon p$. Since the functions $v_k - \chi_k^*$ decays exponentially to zero in the $-\eta_k$ direction its is natural to consider the following approximation

$$\tilde{\phi}_\epsilon^{e,h,\hat{h},p}(x_1, x_2) = \begin{cases} \varphi_k \left(v_k^{\hat{h},p} \left(\frac{x - s_k\eta_k}{\epsilon} \right) \frac{\partial u_0^{h,\hat{h}}}{\partial x_1} - \chi_k^{*,\hat{h},p} E_k(\mu^{h,\hat{h}}) \right) & \text{if } |x'_1 - s_k| < \epsilon p, \\ 0 & \text{if } |x'_1 - s_k| \geq \epsilon p, \end{cases}$$

and $\tilde{\phi}_\epsilon^{h,\hat{h},p} = \sum_{k \in \{1, \dots, N\}} \tilde{\phi}_\epsilon^{e,h,\hat{h},p}$.

- Let $\bar{\phi}_\epsilon^{h,\hat{h},p}$ be a second order accurate finite element approximation in a mesh of size h for the following equation

$$-\nabla A^{\hat{h}} \nabla \psi = 0, \quad \psi = \chi^{*,\hat{h},p} \mu^{h,\hat{h}} \text{ on } \partial\Omega. \quad (11)$$

Remark 2. By construction $\mu^{h,\hat{h}} = 0$ at the corners of Ω , therefore $\chi^* \mu^{h,\hat{h}} \in H^{1/2}(\partial\Omega)$. This implies that Eq.(11) is well posed. In addition $\chi^* \mu^{h,\hat{h}} \in V^h|_{\partial\Omega}$ hence we can look for a numerical solution of Eq.(11) at V^h .

- Approximate θ_ϵ by $\theta_\epsilon^{h,\hat{h},p} := \phi_\epsilon^{r,h,\hat{h},p} + \theta^{*,h,\hat{h},p}$ and finally construct the numerical solution for Eq. (1), $u_\epsilon^{h,\hat{h},p} = u_0^{h,\hat{h}} + \epsilon u_1^{h,\hat{h}} + \epsilon \theta_\epsilon^{h,\hat{h},p}$.

5 Error Analysis

When $p \rightarrow \infty$ and $\hat{h} \rightarrow 0$ we prove in [VS05b] the following estimates.

Theorem 2. *Assume that $a_{ij} \in C^{1,\beta}(\mathfrak{R}^2)$ and $u_0 \in W^{2,\infty}(\Omega)$ ($u_0 \in W^{2,\infty}(\Omega) \cap H^3(\Omega)$). Then there exists a constant c , such that*

$$\begin{aligned} |u_\epsilon - u_h|_{1,h} &\leq c(h + \epsilon) \|u_0\|_{2,\infty} \\ (\|u_\epsilon - u_h\|_0 &\leq c(h^2 + \epsilon^{\frac{3}{2}} + \epsilon h) (\|u_0\|_{2,\infty} + \|u_0\|_3)) \end{aligned}$$

6 Numerical Experiments

In this section, we present some numerical results for solving our model problem with

$$a(x) = \left(\frac{2 + P \sin(2\pi x_1/\epsilon)}{2 + P \cos(2\pi x_2/\epsilon)} + \frac{2 + \sin(2\pi x_2/\epsilon)}{2 + P \sin(2\pi x_1/\epsilon)} \right) I_{2 \times 2}$$

$$f(x) = -1 \quad \text{and} \quad u = 0 \quad \text{on} \quad \partial\Omega.$$

We compare the solution obtained by our method with the solution obtained by a second order accurate finite element method in a fine mesh of size h_f , which we call u_ϵ^* . Tables 1 provide absolute errors estimates for $u_\epsilon^* - u_\epsilon^{h,\hat{h},p}$. We have used $p = 2$, $\hat{h} = 1/128$, $h_f = 1/2048$, and a triangular mesh with continuous piecewise linear functions to approximate χ_h^j and $v_k^{\hat{h},p}$. From Table

Table 1. $u_\epsilon^* - u_\epsilon^{h,\hat{h},p}$ error

$\ \cdot\ _0$ error					
$\epsilon \downarrow$	$h \rightarrow$	1/8	1/16	1/32	1/64
1/16		2.3863e-04	1.5793e-04		
1/32		2.3241e-04	8.0169e-05	1.7773e-05	
1/64		2.3540e-04	5.4314e-05	5.1865e-05	5.9606e-05
$ \cdot _{1,h}$ error					
1/16		0.0097	0.0067		
1/32		0.0086	0.0051	0.0036	
1/64		0.0086	0.0044	0.0025	0.0018

Table 2.

$$\epsilon = 1/64, h = 1/32, h_f = 1/1024$$

	$\ \cdot\ _0$	$ \cdot _{1,h}$
$u_\epsilon^* - u_0^{h,\hat{h}}$	0.0287	0.0215
$u_\epsilon^* - u_0^{h,\hat{h}} - \epsilon u_1^{h,\hat{h}}$	0.0213	0.0026
$u_\epsilon^* - u_0^{h,\hat{h}} - \epsilon u_1^{h,\hat{h}} - \epsilon \bar{\phi}^{h,\hat{h},p}$	5.0450e-05	0.0026
$u_\epsilon^* - u_0^{h,\hat{h}} - \epsilon u_1^{h,\hat{h}} - \epsilon (\bar{\phi}^{h,\hat{h},p} + \tilde{\phi}_\epsilon^{h,\hat{h},p})$	5.1865e-05	0.0025

1, we see that for $\epsilon \ll h$ we have errors of order $O(h^2)$ and $O(h)$ for the L^2 norm and semi norm H^1 respectively. We observe that when we fix h and decrease ϵ the errors almost do not change. This is an evidence that in this case the dominant error term is $O(h)$. Also looking the diagonal values in these tables we see clearly that the numerical error agrees with the theoretical rates from Theorem 2.

Table 2 shows the improvement obtained in the final approximation by considering the numerical approximation for the boundary corrector. We observe a better improvement on the $\|\cdot\|_0$ norm rather than on $|\cdot|_{1,h}$ semi norm. The reason for this is that $\bar{\phi}$ is obtained through the homogenized equation associated to Problem (7), therefore it is a good approximation for $\bar{\theta}_\epsilon$ on $L^2(\Omega)$ norm but not on $|\cdot|_1$ semi norm. The term $\tilde{\phi}_\epsilon$ is defined in a thin boundary layer that mostly force the approximation to satisfies the zero Dirichlet boundary condition.

7 Conclusions

We propose a new method for approximating numerically the solution of Equation (1). This method is strongly based on periodicity of the coefficients a_{ij} , and for this reason it has relative low computational cost with optimal error convergence rate.

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