

Open-source finite element solver for domain decomposition problems

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Outline

GetDP

Results

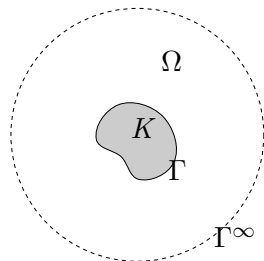
Conclusions and perspectives

GetDP

Results

Conclusions and perspectives

Reference problem



Scattered field u solution of

$$\begin{cases} (\Delta + k^2)u = 0 & \text{in } \Omega := \mathbb{R}^d \setminus \overline{K}, \\ u = -u^{inc} & \text{on } \Gamma, \\ \partial_{\mathbf{n}}u - iku = 0 & \text{on } \Gamma^\infty, \end{cases}$$

Reference problem

Non-overlapping DDM, iteration $n + 1$

For $j = 0, \dots, N_{\text{dom}} - 1$, do ($\Omega := \cup_j \Omega_j$):

1. Compute the fields $u_j^{n+1} := u^{n+1}|_{\Omega_j}$:

$$\begin{cases} (\Delta + k^2)u_j^{n+1} = 0 & \text{in } \Omega_j, \\ u_j^{n+1} = -u^{inc} & \text{on } \Gamma_j, \\ \partial_{\mathbf{n}} u_j^{n+1} - ik u_j^{n+1} = 0 & \text{on } \Gamma_j^\infty, \\ \partial_{\mathbf{n}} u_j^{n+1} + \mathcal{S} u_j^{n+1} = g_{ij}^n & \text{on } \Sigma_{ij} \quad (\forall i \neq j). \end{cases}$$

2. Update the data g_{ji}^{n+1}

$$g_{ji}^{n+1} = -g_{ij}^n + 2\mathcal{S} u_j^{n+1}, \quad \text{on } \Sigma_{ij}.$$

Where:

- ▶ $\Sigma_{ij} := \partial\Omega_i \cap \partial\Omega_j$, $\Gamma_j = \Gamma \cap \partial\Omega_j$ and $\Gamma_j^\infty = \Gamma^\infty \cap \partial\Omega_j$
- ▶ \mathcal{S} : transmission operator (Sommerfeld, OO2, GIBC, ...)

Reference problem

Recast the DDM into the linear system:

$$(\mathcal{I} - \mathcal{A})g = b, \quad (1.1)$$

where $\mathcal{I} =$ identity operator and ...

$b = (b_{ij})_{j \neq i}$, with

$$b_{ij} = 2\mathcal{S}v_j \quad (\Sigma_{ij}),$$

with

$$\begin{cases} (\Delta + k^2)v_j = 0 & (\Omega_j), \\ v_j = -u^{inc} & (\Gamma_j), \\ \partial_{\mathbf{n}}v_j - ikv_j = 0 & (\Gamma_j^\infty), \\ \partial_{\mathbf{n}}v_j + \mathcal{S}v_j = 0 & (\Sigma_{ij}). \end{cases}$$

$g = (g_{ij})_{j \neq i}$, with

$$(\mathcal{A}g)_{ji} = -g_{ij} + 2\mathcal{S}w_j \quad (\Sigma_{ij}),$$

with

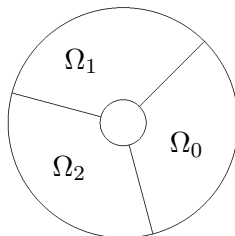
$$\begin{cases} (\Delta + k^2)w_j = 0 & (\Omega_j), \\ w_j = 0 & (\Gamma_j), \\ \partial_{\mathbf{n}}w_j - ikw_j = 0 & (\Gamma_j^\infty), \\ \partial_{\mathbf{n}}w_j + \mathcal{S}w_j = g_{ij} & (\Sigma_{ij}). \end{cases}$$

System (1.1) can be solved using a Krylov subspaces solver (gmres, ...).

Reference problem

Main steps

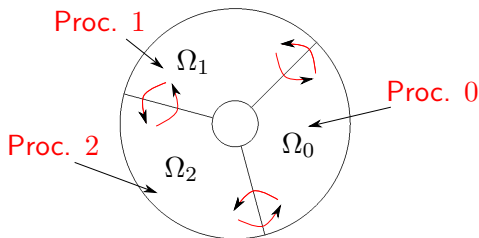
1. Compute b : solve N_{dom} (Helmholtz + surface PDE)
2. Iterative linear solver to solve $(\mathcal{I} - \mathcal{A})g = b$:
 - ▶ Solve N_{dom} (Helmholtz + surface PDE): $(g_{ij}^{n+1})_{j \neq i}$
3. Compute u : solve N_{dom} Helmholtz



Reference problem

Main steps in parallel

1. Compute b : solve N_{dom} (Helmholtz + surface PDE) in parallel
2. Iterative linear solver to solve $(\mathcal{I} - \mathcal{A})g = b$:
 - ▶ Exchange data between subdomains/MPI process
 - ▶ Solve N_{dom} (Helmholtz + surface PDE) in parallel: $(g_{ij}^{n+1})_{j \neq i}$
3. Exchange data between subdomains/MPI process
4. Compute u : solve N_{dom} Helmholtz in parallel



GetDP

GetDP=General Environment for the Treatment of Discrete Problems

Authors

- ▶ C. Geuzaine and P. Dular

History

- ▶ Started at the end of 1996 (first binary release mid 1998)
- ▶ Open-Source under GNU GPL (since 2004)

Design

- ▶ Small, fast, no GUI
- ▶ End-users: not yet another library
- ▶ Limit external dependencies to a minimum

How ?

- ▶ Clear *mathematical structure*

Languages

- ▶ C/C++ with PETSc

GetDP: DD add-on

Motivation of the add-on

Solve a linear system $AX = b$ with a “matrix-free” vector product.

Goal of the add-on

- ▶ DD made simple: passing from mono-domain to multi-domain must not be painful
- ▶ Parallelization: easy and prevent the user from writing in MPI
- ▶ General method: no restriction to a PDE, a Krylov solver, ...
- ▶ Fast and efficient
- ▶ Robust and scalable
- ▶ Open-source

GetDP: DD add-on

When the user have a code solving a mono-domain PDE with GetDP ...

What the user must do...

- ▶ All the mathematics of DDM
- ▶ Build/Decompose mesh with e.g. GMSH (some plugins exist)
- ▶ Define the matrix-free vector product
- ▶ Define parameters: solver, tolerance, ...

If(mpirun)

- ▶ Chose a distribution of the domains/unknown to MPI process
- ▶ Opt.: specify subdomains' neighbors (speed up)

What GetDP will do...

- ▶ Manages the iterative linear solver (PETSc)
- ▶ If(mpirun): Automatically exchanges data between process (MPI)

GetDP: DD add-on

Remark: surface unknown g are interpolable

- ▶ Mixed formulations
- ▶ Non conform mesh at interfaces

GetDP: code

Main steps in parallel

1. Compute b : solve N_{dom} Helmholtz + N_{dom} surface PDE in parallel
2. Iterative linear solver to solve $(\mathcal{I} - \mathcal{A})g = b$:
 - ▶ Exchange data between subdomains/MPI process
 - ▶ Solve N_{dom} Helmholtz + N_{dom} surface PDE in parallel:
 $(g_{ij}^{n+1})_{j \neq i}$
3. Exchange data between subdomains/MPI process
4. Compute u : solve N_{dom} Helmholtz

GetDP: code

Weak formulations ($\mathcal{S} := -ik$ (Sommerfeld) and $\mathcal{B} := -ik$ (Sommerfeld)).

For $j = 0, \dots, N_{\text{dom}} - 1$ ($v_j :=$ test functions):

$$\underbrace{\int_{\Omega_j} \nabla u_j \cdot \overline{\nabla v_j} - \int_{\Omega_j} k^2 u_j \cdot \overline{v_j}}_{\text{Helmholtz equation}} - \underbrace{\int_{\Gamma_j^\infty} iku_j \cdot \overline{v_j}}_{\text{Sommerfeld ABC}} - \underbrace{\int_{\Sigma_j} g_j^{\text{in}} \cdot \overline{v_j} - \int_{\Sigma_j} iku_j \cdot \overline{v_j}}_{\text{Transmission condition}} = 0$$

For j In {0:N_DOM-1}

[...]

Galerkin { [Dof{Grad u~{j}} , {Grad u~{j}}] ;
In Omega~{j}; Jacobian JVol ; Integration I1 ; }

Galerkin { [-k^2 * Dof{u~{j}} , {u~{j}}] ;
In Omega~{j}; Jacobian JVol ; Integration I1 ; }

Galerkin { [-I[] * k * Dof{u~{j}} , {u~{j}}] ;
In GammaInf~{j}; Jacobian JSur ; Integration I1 ; }

Galerkin { [-g_in~{j}[] , {u~{j}}] ;
In Sigma~{j}; Jacobian JSur; Integration I1 ; }

Galerkin { [-I[] * k * Dof{u~{j}} , {u~{j}}] ;
In Sigma~{j}; Jacobian JSur ; Integration I1 ; }

[...]

EndFor

GetDP: code

More complicated transmission condition (OO2: Gander, Magoulès, Nataf, 2002):

$$au_j - b\Delta_{\Sigma_j} u_j - g_j^{in} = 0, \quad \text{on } \Sigma_j.$$

Weak formulation ($v_j :=$ test function):

$$\int_{\Sigma_j} 2au_j \cdot \bar{v}_j - \int_{\Sigma_j} b\nabla_{\Sigma_j} u_j \cdot \nabla_{\Sigma_j} \bar{v}_j + \int_{\Sigma_j} g_j^{in} \cdot \bar{v}_j = 0.$$

```
Galerkin { [ a[]* Dof{u~{j}} , {u~{j}} ] ;  
  In Sigma~{j}; Jacobian JSur ; Integration I1 ; }  
Galerkin { [ -b[] * Dof{d u~{j}} , {d u~{j}} ] ;  
  In Sigma~{j}; Jacobian JSur ; Integration I1 ; }  
Galerkin { [ - g_in~{j}[] , {u~{j}} ] ;  
  In Sigma~{j}; Jacobian JSur ; Integration I1 ; }
```

GetDP: code

Main steps in parallel

1. Compute b : solve N_{dom} (Helmholtz + surface PDE) in parallel
2. Iterative linear solver to solve $(\mathcal{I} - \mathcal{A})g = b$:
 - ▶ Exchange data between subdomains/MPI process
 - ▶ Solve N_{dom} (Helmholtz + surface PDE) in parallel: $(g_{ij}^{n+1})_{j \neq i}$
3. Exchange data between subdomains/MPI process
4. Compute u : solve N_{dom} Helmholtz

GetDP: code

Acoustic:

```
IterativeLinearSolver["I-A", solver, tol, maxit, ...]  
{  
  SetCommSelf ; // Sequential mode  
  For ii In {0: #ListOfDom()-1}  
    j = ListOfDom(ii) ;  
    // Solve Helmholtz on  $\Omega_j$   
    GenerateRHSGroup[Helmholtz~{j}, Sigma~{j}] ;  
    SolveAgain[Helmholtz~{j}] ;  
    // Compute  $g_{ji}$   
    GenerateRHSGroup[ComputeG~{j}, Sigma~{j}] ;  
    SolveAgain[ComputeG~{j}] ;  
  EndFor  
  // Update  $g_{ji}$  in memory  
  For ii In {0: #ListOfDom()-1}  
    j = ListOfDom(ii) ;  
    PostOperation[g_out~{j}] ;  
  EndFor  
  SetCommWorld ;// Parallel mode  
}
```

GetDP: code

And for Maxwell's equation . . .

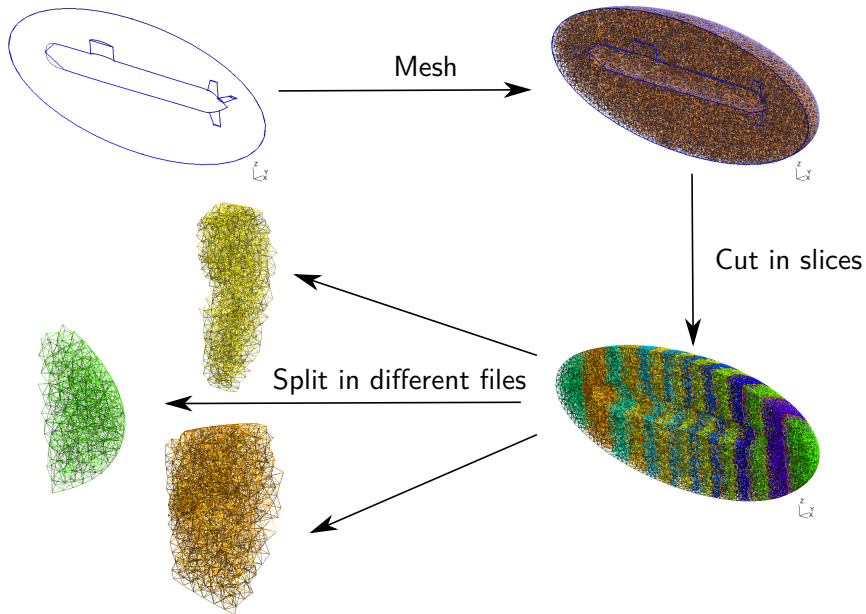
```
IterativeLinearSolver["I-A", solver, tol, maxit, ...]
{
  SetCommSelf ; // Sequential mode
  For ii In {0: #ListOfDom()-1}
    j = ListOfDom(ii) ;
    // Solve Maxwell on  $\Omega_j$ 
    GenerateRHSGroup[Maxwell~{j}, Sigma~{j}] ;
    SolveAgain[Maxwell~{j}] ;
    // Compute  $g_{ji}$ 
    GenerateRHSGroup[ComputeG~{j}, Sigma~{j}] ;
    SolveAgain[ComputeG~{j}] ;
  EndFor
  // Update  $g_{ji}$  in memory
  For ii In {0: #ListOfDom()-1}
    j = ListOfDom(ii) ;
    PostOperation[g_out~{j}] ;
  EndFor
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}
```

GetDP

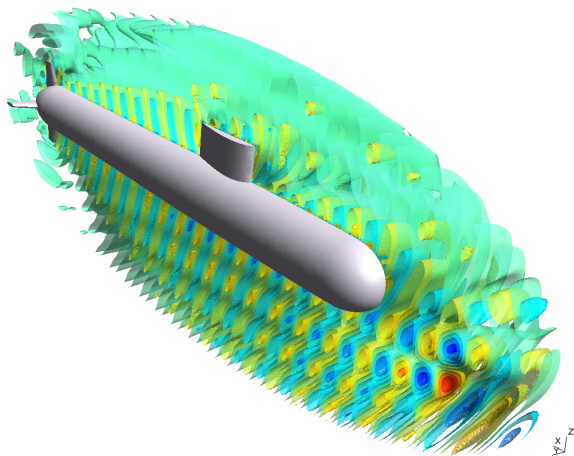
Results

Conclusions and perspectives

Acoustic: 3D submarine



Acoustic: 3D submarine



Submarine problem with 16 subdomains: iso-surfaces of the real part of the scattered field for $k = 41\pi$.

Acoustic: 3D submarine

Vega Cluster (ULB, Belgium): 42 nodes, each with 256GB of RAM and 4 AMD 6722 processors, with 16 cores at 2.1GHz (MPI/OpenBlas).

$$k = 10\pi \text{ and } L_{sub} = 1$$

Nb. domains	Nb. nodes	Nb. MPI/nodes	Nb. threads/MPI	Nb. vertices (M.)	Nb. iterations	CPU time (min)	Max RAM (GB)	Size volume PDE	Size surface PDE	Size GMRES
16	16	1	16	40	127	302	137	27×10^5	10×10^4	9×10^6
32	16	2	8	2.5	113	9	3	1.2×10^5	1.6×10^4	2.9×10^6
				5	121	21	7	2.1×10^5	2.5×10^4	4.5×10^6
				10	129	42	13	4.1×10^5	4×10^4	7.2×10^6
				20	158	90	?	8×10^5	6.7×10^4	12×10^6
				40	171	205	60	15×10^5	10×10^4	18×10^6
	16	2	8	40	171	182	63	15×10^5	10×10^4	18×10^6
				80	184	495	141	29×10^5	16×10^4	29×10^6
				120	192	795	220	42×10^5	21×10^4	38×10^6
64	32	2	16	40	240	250	40	8×10^5	10×10^4	38×10^6
				80	259	817	85	16×10^5	16×10^4	60×10^6
				120	270	1072	118	23×10^5	21×10^4	78×10^6

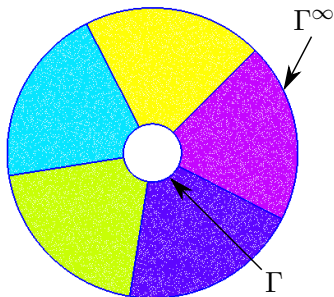
Acoustic: 3D submarine

NIC4 cluster (ULg, Belgium): 120 nodes, each with 64GB of RAM and 2 Intel E2650 processors with 8 cores at 2GHz (MPI/MKL).

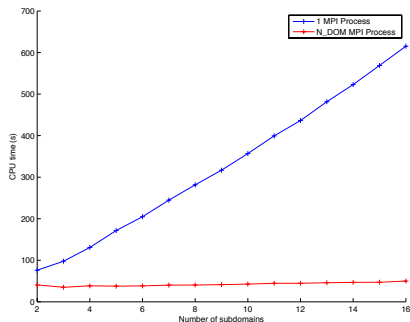
$k = 10\pi$ and $L_{sub} = 1$.

Nb. domains	Nb. nodes	Nb. MPI/nodes	Nb. threads/MPI	Nb. vertices (M.)	Nb. iterations	CPU time (min)	Max RAM (GB)	Size volume PDE	Size surface PDE	Size GMRES
32	32	1	16	40	171	100	59.5	14.9×10^5	10^5	1.8×10^7
64	64	1	16	40	240	160	39.4	8.8×10^5	10^5	3.8×10^7
96	96	1	16	40	303	195	36.3	6.7×10^5	10^5	5.7×10^7
120	120	1	16	80	371	399	63.0	10.8×10^5	1.6×10^5	11.4×10^7

Acoustic: scalability (2D)

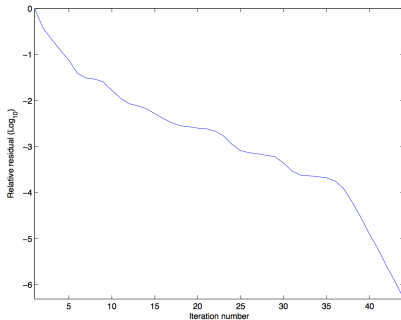
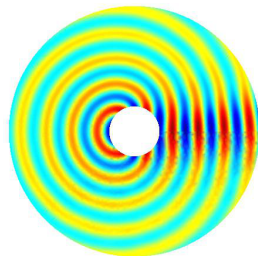
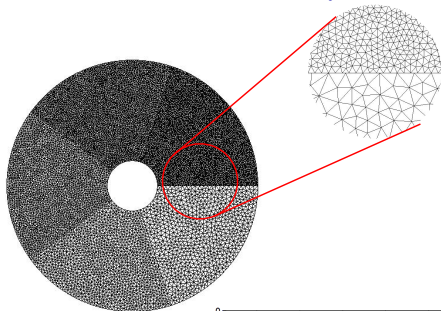


Circle-pie decomposition (2D).



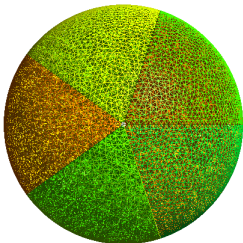
CPU time vs. N_{dom} with 1 or N_{dom} number of MPI process.

Acoustic: non conform (simple case)

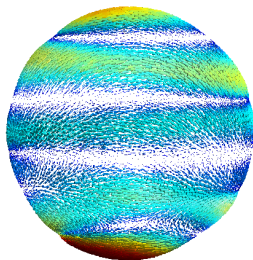


$$k = 2\pi$$
$$N_{dom} = 5$$
$$\text{tol: } 10^{-6}$$

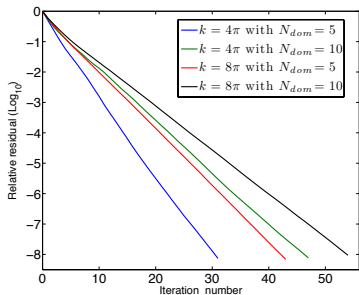
Electromagnetism 3D



Y
Z X



Real part of surface current
0.00138 0.666 1.33
X Z
Y



- ▶ Perfectly conducting sphere
- ▶ Two concentric spheres
- ▶ $N_{dom} = 5$ or 10

GetDP

Results

Conclusions and perspectives

Conclusions

Our software...

- ▶ Quite easy to pass from mono-domain to multi-domain
- ▶ Fast and efficient
- ▶ Has been successfully tested on cluster
- ▶ Adapted to scalar/vector/tensor unknown

What can be done with it...

- ▶ 1D/2D/3D without change (GetDP is 3D native)
- ▶ Automatic partitioning (“waveguide-style”)
- ▶ With or without overlap
- ▶ Mixed formulations
- ▶ Non conform mesh at interfaces (interpolation)
- ▶ Right (or left) preconditioning: $(\mathcal{I} - \mathcal{A})\mathcal{F}^{-1}\tilde{g} = b$ with $\mathcal{F}g = \tilde{g}$.

Perspectives

- ▶ Publish DDM codes online (acoustic/electromagnetism)
- ▶ Documentation
- ▶ Computational optimizations (storage of unknown, . . .)
- ▶ Optimize/Make easier mesh decomposition (topological tools)
- ▶ Really automatic partitioning algorithms (metis/chaco)
- ▶ Hope some of you will use it :-)

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Thank you very much !