

Multiscale Spectral Generalized Finite Element Methods for Discontinuous Galerkin Schemes

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1 Motivation and Model Setup

This article presents a multiscale spectral generalized finite element method (MS-GFEM) tailored to discontinuous Galerkin (DG) discretizations of partial differential equations (PDEs). Our work is motivated by two problem classes: heterogeneous Stokes flows, where DG discretizations improve mass conservation, and convection-dominated diffusion, where DG fluxes enhance stability. Previous work established nearly exponential error decay for MS-GFEM in the Hilbert-space setting [3] and for continuous Galerkin methods [4]. As a first step toward extending that analysis to DG discretizations, we prove nearly exponential decay of the MS-GFEM approximation error for second-order elliptic PDEs with highly heterogeneous diffusion discretized by a weighted symmetric interior-penalty discontinuous Galerkin method.

Let $\Omega \subset \mathbb{R}^d$, $d \in \{2, 3\}$, be a polygonal Lipschitz domain. We consider the following second-order elliptic PDE with homogeneous Dirichlet boundary conditions:

$$\begin{cases} -\operatorname{div}(\nu \nabla u) = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1)$$

where $f \in L^2(\Omega)$ and $\nu \in L^\infty(\Omega)$. We assume that $\nu_{\min} \leq \nu(\mathbf{x}) \leq \nu_{\max}$ holds for almost all $\mathbf{x} \in \Omega$ for some constants $\nu_{\max}, \nu_{\min} > 0$. The weak form of (1) is based on the Sobolev space $H_0^1(\Omega)$ of H^1 -functions vanishing on the boundary $\partial\Omega$. Given $f \in L^2(\Omega)$, the weak form of (1) seeks a function $u \in H_0^1(\Omega)$ such that

$$\int_{\Omega} \nu \nabla u \cdot \nabla v \, dx = \int_{\Omega} f v \, dx =: \mathcal{F}(v) \quad \forall v \in H_0^1(\Omega). \quad (2)$$

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By the Poincaré-Friedrichs inequality and the uniform bound on ν , we obtain that the bilinear form in (2) defines an inner product on $H_0^1(\Omega)$. Since \mathcal{F} is a bounded linear functional, the Riesz representation theorem yields well-posedness of (2). For any subdomain $S \subset \Omega$, we define $\mathcal{F}_S(v) := \int_S f v \, dx$ for all $v \in L^2(S)$. We write $(\cdot, \cdot)_S$ and $\langle \cdot, \cdot \rangle_F$ for the L^2 -inner products on subdomains S and faces F , and use \lesssim for inequalities up to constants independent of model parameters and mesh size.

2 Discontinuous Galerkin Method

For ease of presentation, we employ a matching shape-regular simplicial mesh \mathbb{T}_h (cf. [2, Section 1.4.1]) and define $V_h := \mathcal{P}_1^{\text{disc}}(\Omega, \mathbb{T}_h)$. For all $T \in \mathbb{T}_h$, we denote by h_T the diameter of T and define the mesh size $h := \max_{T \in \mathbb{T}_h} h_T$. We assume that the coefficient ν is resolved by the mesh, i.e., ν is piecewise constant with respect to \mathbb{T}_h . The sets of interior and boundary faces of \mathbb{T}_h are denoted by \mathbb{F}_h^i and \mathbb{F}_h^∂ , respectively. For an interior face $F = \partial T_1 \cap \partial T_2$, we introduce $\nu_i = \nu|_{T_i}$, and we set $\nu_1 = \nu_2 = \nu$ for boundary edges. To deal with varying ν , we introduce ν -dependent weights in the penalty and consistency terms ([2, Chapter 4.5]) and define the sum operators

$$\llbracket u \rrbracket_w := \frac{2\nu_2}{\nu_1 + \nu_2} u_1 + \frac{2\nu_1}{\nu_1 + \nu_2} u_2, \quad \llbracket u \rrbracket := u_1 + u_2, \quad u \in V_h^d.$$

For any subdomain $D \subset \Omega$, we define $\mathbb{F}_h^i(D) := \{F \cap D : F \in \mathbb{F}_h^i\}$ and $\mathbb{F}_h^\partial(D) := \{F \cap \partial D : F \in \mathbb{F}_h^\partial\}$, and we introduce the bilinear forms

$$\begin{aligned} B_D^i(u, v) &= B_{p,D}^i(u, v) - B_{c,D}^i(u, v) - B_{c,D}^i(v, u), \\ B_D^\partial(u, v) &= B_{p,D}^\partial(u, v) - B_{c,D}^\partial(u, v) - B_{c,D}^\partial(v, u), \\ B_D(u, v) &= (\nu \nabla_h u, \nabla_h v)_D + B_D^i(u, v) + B_D^\partial(u, v), \end{aligned}$$

with

$$\begin{aligned} B_{c,D}^i(u, v) &= \frac{1}{2} \langle \llbracket \nu \nabla_h u \rrbracket_w, \llbracket v \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(D)}, & B_{p,D}^i(u, v) &= \langle \gamma_h^2 \llbracket u \mathbf{n} \rrbracket, \llbracket v \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(D)}, \\ B_{c,D}^\partial(u, v) &= \langle \nu \nabla_h u, v \mathbf{n} \rangle_{\mathbb{F}_h^\partial(D)}, & B_{p,D}^\partial(u, v) &= 2 \langle \gamma_h^2 u \mathbf{n}, v \mathbf{n} \rangle_{\mathbb{F}_h^\partial(D)}, \end{aligned}$$

where \mathbf{n} is the elementwise unit outward normal vector, $\langle \cdot, \cdot \rangle_{\mathbb{F}_h^i(D)}$ and $\langle \cdot, \cdot \rangle_{\mathbb{F}_h^\partial(D)}$ denote the L^2 -inner products integrated over the union of all faces in $\mathbb{F}_h^i(D)$ and $\mathbb{F}_h^\partial(D)$, respectively. Further, $\gamma_h^2 = \frac{\gamma_0^2}{h_F} \frac{2\nu_1\nu_2}{\nu_1 + \nu_2}$ with a stabilization parameter, γ_0 , and the face diameter, h_F . Note that $\llbracket u \mathbf{n} \rrbracket$ describes a jump term by definition.

If $D = \Omega$, we drop the subscript D in the notations above. The discrete formulation of (2) is to find $u^e \in V_h$ such that $B(u^e, v) = \mathcal{F}(v)$ for all $v \in V_h$. For later use, we define D^+ as the union of all $T \in \mathbb{T}_h$ with $T \cap D \neq \emptyset$ and D^- as the union of all $T \in \mathbb{T}_h$ with $\bar{T} \cap D^c = \emptyset$, such that $D^- \subset D \subset D^+$. Throughout this paper, complements are taken with respect to Ω .

3 MS-GFEM for DG Discretizations of Elliptic PDEs

Consider a mesh-resolved overlapping domain decomposition $\{\omega_j\}_{j=1}^M, \cup_{j=1}^M \omega_j = \Omega$, and define a partition of unity $\{\chi_j\}_{j=1}^M$ subordinate to this decomposition satisfying $\text{supp}(\chi_j) \subset \overline{\omega_j}, 0 \leq \chi_j \leq 1, \sum_{j=1}^M \chi_j \equiv 1, \chi_j \in \mathcal{P}_1(\Omega, \mathbb{T}_h)$. MS-GFEM builds local approximations on so-called oversampling domains ω_j^* satisfying $\omega_j \subset \omega_j^* \subset \Omega$ as the sum of a local source solution u_j^p with $u_j^p = 0$ on $\partial\omega_j^* \cap \partial\Omega$, cf. (6), and a correction from an optimal n_j -dimensional spectral coarse space $S_{n_j}(\omega_j)$, cf. (7). The global approximation is then assembled using a partition of unity, $u^p := \sum_{j=1}^M \chi_j u_j^p, S_n(\Omega) := \{\sum_{j=1}^M \chi_j \phi_j : \phi_j \in S_{n_j}(\omega_j)\}, n = \sum_{j=1}^M n_j$, and the MS-GFEM approximation is defined as $u^G = u^p + u^s$ with $u^s \in S_n(\Omega)$ satisfying $B(u^s, v) = \mathcal{F}(v) - B(u^p, v)$ for all $v \in S_n(\Omega)$. The key assumptions for the exponential error decay are a Caccioppoli inequality and a weak approximation property. We verify these, together with the remaining assumptions of [3], to show that our method fits into their general framework. For a detailed description of the abstract MS-GFEM and the complete statement of all assumptions, we refer the reader to [3].

Verification of [3, Assumption 2.3]. (i) For $D \subset \Omega$, we define $\mathcal{H}(D) := \{v|_D : v \in V_h\}$ and $\mathcal{H}_0(D) := \{v|_D : v \in V_h, v = 0 \text{ on } D \setminus D^-\}$, both with the inner product

$$\langle \cdot, \cdot \rangle_{\mathcal{H}(D)} = (v \nabla_h \cdot, \nabla_h \cdot)_D + \langle \gamma_h^2 \llbracket \cdot \mathbf{n} \rrbracket, \llbracket \cdot \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(D)} + \langle \gamma_h^2 \cdot, \cdot \rangle_{\mathbb{F}_h^\partial(D)} + \langle \cdot, \cdot \rangle_D.$$

Clearly, $\mathcal{H}_0(D) \subset \mathcal{H}(D)$ for arbitrary subdomains $D \subset \Omega$, and $\mathcal{H}_0(\Omega) = \mathcal{H}(\Omega)$.

(ii) For $D \subset D^*$, we define $E_{D,D^*} : \mathcal{H}_0(D) \rightarrow \mathcal{H}_0(D^*)$ via $E_{D,D^*}(v) = v$ on D^- and $E_{D,D^*}(v) = 0$ elsewhere. We want to show that $\|E_{D,D^*}(v)\|_{\mathcal{H}_0(D^*)} = \|v\|_{\mathcal{H}_0(D)}$ for all $v \in \mathcal{H}_0(D)$. Since $E_{D,D^*}(v)$ and v agree on D^- and vanish elsewhere, the volume contributions to the norms are equal. Next, we consider the contributions from interior faces. Let $F \in \mathbb{F}_h^i$ with $F = \partial T_1 \cap \partial T_2$. We want to show

$$\langle \gamma_h^2 \llbracket E_{D,D^*}(v) \mathbf{n} \rrbracket, \llbracket E_{D,D^*}(v) \mathbf{n} \rrbracket \rangle_{F \cap D^*} = \langle \gamma_h^2 \llbracket v \mathbf{n} \rrbracket, \llbracket v \mathbf{n} \rrbracket \rangle_{F \cap D}. \quad (3)$$

If $F \subset D$, then $E_{D,D^*}(v)|_{T_1 \cup T_2} = v|_{T_1 \cup T_2}$ and $F \cap D = F \cap D^*$, hence (3) holds. If $F \subset D^c$, then $E_{D,D^*}(v)|_{T_1 \cup T_2} = 0$ and $F \cap D = \emptyset$, hence both sides of (3) vanish. If $F \cap \partial D \neq \emptyset$, then $E_{D,D^*}(v)|_{T_1 \cup T_2} = v|_{T_1 \cup T_2} = 0$ and both sides of (3) vanish. We proceed similarly for boundary faces $F \in \mathbb{F}_h^\partial$ with $F \subset \partial T$ to show that

$$\langle \gamma_h^2 E_{D,D^*}(v), E_{D,D^*}(v) \rangle_{F \cap \partial D^*} = \langle \gamma_h^2 v, v \rangle_{F \cap \partial D}. \quad (4)$$

If T is not contained in D^- , then $E_{D,D^*}(v)|_T = 0$ and $v|_T = 0$ and thus both sides of (4) vanish. If T is contained in D^- , then $E_{D,D^*}(v)|_T = v|_T$ and since F is a boundary face with $T \subset D \subset D^*$, we have $F \subset \partial D$ and $F \subset \partial D^*$. Hence, $F \cap \partial D = F = F \cap \partial D^*$ and both sides of (4) are equal.

(iii) For $D \subset D^*$, we define $R_{D^*,D} : \mathcal{H}(D^*) \rightarrow \mathcal{H}(D)$, $R_{D^*,D}(v) = v|_D$. Due to the definition of the norm on $\mathcal{H}(D)$, we have $\|R_{D^*,D}(v)\|_{\mathcal{H}(D)} \leq \|v\|_{\mathcal{H}(D^*)}$.

(iv) For arbitrary $D \subset D^*$, $u \in \mathcal{H}(D^*)$ and $v \in \mathcal{H}_0(D)$, we have $B_D(u|_D, v) = B_{D^*}(u, E_{D, D^*}(v))$ since v vanishes on $D \setminus D^-$. \square

We denote by $I_h: \{v : v|_T \in C^\infty(T) \text{ for all } T \in \mathbb{T}_h\} \rightarrow \mathcal{H}(\Omega)$ the elementwise defined Lagrangian interpolation operator and define the partition of unity operator $P_j: \mathcal{H}(\omega_j) \rightarrow \mathcal{H}_0(\omega_j)$, $P_j(u) = I_h(\chi_j u)$. Boundedness of this operator is shown via the following lemma.

Lemma 1 *Let $u \in \mathcal{H}(\omega)$, $\chi \in \mathcal{P}_1(\omega, \mathbb{T}_h)$. Then, $\|\chi u - I_h(\chi u)\|_{\mathcal{H}_0(\omega)} \lesssim \|\chi u\|_{\mathcal{H}(\omega)}$.*

Proof. First, we note that χu is piecewise polynomial due to $\chi \in \mathcal{P}_1(\omega, \mathbb{T}_h)$. Therefore, an inverse inequality and elementwise interpolation properties of I_h yield

$$\begin{aligned} \|v^{1/2} \nabla_h(\chi u - I_h(\chi u))\|_{L^2(\omega)} &\lesssim \|v^{1/2} \nabla_h(\chi u)\|_{L^2(\omega)}, \\ \|\chi u - I_h(\chi u)\|_{L^2(\omega)} &\lesssim \|\chi u\|_{L^2(\omega)}. \end{aligned}$$

Next, we consider the jump terms. For all interior faces $F = \partial T_1 \cap \partial T_2$, observe that $\langle \llbracket \mathbf{a} \mathbf{n} \rrbracket, \llbracket \mathbf{b} \mathbf{n} \rrbracket \rangle_F \leq (\|a|_{T_1}\|_{L^2(F)} + \|a|_{T_2}\|_{L^2(F)}) (\|b|_{T_1}\|_{L^2(F)} + \|b|_{T_2}\|_{L^2(F)})$ for arbitrary a and b , such that applying the discrete trace inequality [2, Lemma 1.46], elementwise interpolation properties and [2, Lemma 1.43] yields

$$\begin{aligned} &\langle \gamma_h^2 \llbracket (\chi u - I_h(\chi u)) \mathbf{n} \rrbracket, \llbracket (\chi u - I_h(\chi u)) \mathbf{n} \rrbracket \rangle_F \\ &\lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} h_{T_{\min}}^{-2} \|\chi u - I_h(\chi u)\|_{L^2(T_1 \cup T_2)}^2 \lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} h_{T_{\min}}^{-2} h_{T_{\max}}^2 \|\nabla_h(\chi u)\|_{L^2(T_1 \cup T_2)}^2 \\ &\lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} \sum_{i=1}^2 \frac{1}{\nu_i} \|v_i^{1/2} \nabla_h(\chi u)\|_{L^2(T_i)}^2 \leq \|v^{1/2} \nabla_h(\chi u)\|_{L^2(T_1 \cup T_2)}^2, \end{aligned} \quad (5)$$

where $h_{T_{\min}} = \min\{h_{T_1}, h_{T_2}\}$ and $h_{T_{\max}} = \max\{h_{T_1}, h_{T_2}\}$. Summing over all interior faces of ω , we conclude

$$\langle \gamma_h^2 \llbracket (\chi u - I_h(\chi u)) \mathbf{n} \rrbracket, \llbracket (\chi u - I_h(\chi u)) \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(\omega)} \lesssim \|v^{1/2} \nabla_h(\chi u)\|_{L^2(\omega)}^2.$$

Boundary faces can be treated similarly. Finally, we combine all estimates to obtain the statement of the lemma. \square

Corollary 1 *Let $u \in \mathcal{H}(\omega)$ and $\chi \in \mathcal{P}_1(\omega, \mathbb{T}_h)$. Then,*

$$\|I_h(\chi u)\|_{\mathcal{H}_0(\omega)} \lesssim \|\chi u\|_{\mathcal{H}(\omega)} \lesssim \sqrt{1 + \|\nabla_h \chi\|_{L^\infty(\omega)}^2} \|u\|_{\mathcal{H}(\omega)}.$$

Verification of [3, Assumption 2.9]. Let $\psi_j \in \mathcal{H}_0(\omega_j^*)$ be the unique solution of

$$B_{\omega_j^*}(\psi_j, v) = \mathcal{F}_{\omega_j^*}(v) \quad \forall v \in \mathcal{H}_0(\omega_j^*) \quad (6)$$

and define the particular solution as $u_j^p := \psi_j|_{\omega_j}$. Note that $B_{\omega_j^*}$ does not contain face integrals over the interior subdomain boundary. However, since we define problem (6) on $\mathcal{H}_0(\omega_j^*)$, it is well-posed. \square

Verification of [3, Assumption 2.13]. For every domain $\omega_j \subset D \subset \omega_j^*$, we define $B_D^+(\cdot, \cdot) := (v \nabla_h \cdot, \nabla_h \cdot)_D + \langle \gamma_h^2 \llbracket \cdot \mathbf{n} \rrbracket, \llbracket \cdot \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(D)} + \langle \gamma_h^2 \llbracket \cdot \mathbf{n} \rrbracket, \llbracket \cdot \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^\partial(D)}$. If $B_D^+(u, v) = 0$ holds for all $v \in \mathcal{H}(D)$, then this holds in particular for $v = u$. Thus, the gradient terms and jumps over inner faces in the definition of B_D^+ imply that u is constant on D . Conversely, if u is constant, the jump terms and gradients in the definition of B_D^+ vanish and $B_D^+(u, v) = 0$ holds for all $v \in \mathcal{H}(D)$. Hence, [3, Assumption 2.13] holds with $\mathcal{K}_D = \{0\}$ if D is a boundary subdomain and with $\mathcal{K}_D = \text{span}(1)$ if D is an interior subdomain. \square

For the construction of the coarse space, we define the space of discretely locally harmonic functions, $\mathcal{H}_B(\omega_j^*) := \{u \in \mathcal{H}(\omega_j^*) : B_{\omega_j^*}(u, v) = 0 \ \forall v \in \mathcal{H}_0(\omega_j^*)\}$. Consider the generalized eigenvalue problem of finding $\lambda \in [0, +\infty]$, $\varphi \in \mathcal{H}_B(\omega_j^*)$ such that $B_{\omega_j^*}^+(P_j(\varphi|_{\omega_j}), P_j(v|_{\omega_j})) = \lambda B_{\omega_j^*}^+(\varphi, v)$ for all $v \in \mathcal{H}_B(\omega_j^*)$. Denoting the k -th eigenpair as $(\lambda_{j,k}, \varphi_{j,k})$, where $\lambda_{j,1} \geq \lambda_{j,2} \geq \dots$, the local approximation space is built from the eigenfunctions corresponding to the n_j largest eigenvalues:

$$S_{n_j}(\omega_j) := \text{span}\{\varphi_{j,1}|_{\omega_j}, \dots, \varphi_{j,n_j}|_{\omega_j}\}. \quad (7)$$

Next, we verify the two central assumptions of [3]. For $D \subset \Omega$, we denote by $C_B(D)$ and $\alpha_B(D)$ the continuity and coercivity constants of the bilinear form B_D with respect to the (semi-)norm $\|\cdot\|_{B^+, D}$ induced by B_D^+ . Note that $C_B(D)$ and $\alpha_B(D)$ are independent of ν , which can be shown as in [2, Lemma 4.51, Lemma 4.52].

Lemma 2 (Caccioppoli inequality, [3, Assumption 3.1]) *Let $\omega \subset \omega^* \subset \Omega$ and $u \in \mathcal{H}_B(\omega^*)$ with $\delta = \text{dist}(\omega, \partial\omega^* \setminus \partial\Omega) > 3 \max_{K \in \mathbb{T}_h: K \cap \omega^* \setminus \omega \neq \emptyset} h_K$. Then,*

$$\|u|_\omega\|_{B^+, \omega} \lesssim \nu_{\max}^{1/2} \delta^{-1} \|u\|_{L^2(\omega^* \setminus \omega)}. \quad (8)$$

Proof. Let $\eta \in \mathcal{P}_1(\omega^*, \mathbb{T}_h)$ be a cut-off function with $\text{supp}(\eta) \subset \overline{(\omega^*)^-}$, $\eta = 1$ on ω^+ and $|\nabla_h \eta| \leq C_\eta \delta^{-1}$. We proceed as in [4]. By definition,

$$B_{\omega^*}(\eta u, \eta u) = (\nu \nabla_h(\eta u), \nabla_h(\eta u))_{\omega^*} + B_{\omega^*}^i(\eta u, \eta u) + B_{\omega^*}^\partial(\eta u, \eta u). \quad (9)$$

For the second term in (9), we use that η is continuous along mesh faces to compute

$$\begin{aligned} B_{\omega^*}^i(\eta u, \eta u) &= \langle \gamma_h^2 \llbracket \eta u \mathbf{n} \rrbracket, \llbracket \eta u \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(\omega^*)} - \langle \llbracket \nu \nabla_h(\eta u) \rrbracket_w, \llbracket (\eta u) \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(\omega^*)} \\ &= \langle \gamma_h^2 \llbracket u \mathbf{n} \rrbracket, \llbracket \eta^2 u \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(\omega^*)} - \langle \llbracket \nu \eta \nabla_h u + \nu u \nabla_h \eta \rrbracket_w, \llbracket (\eta u) \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(\omega^*)} \\ &= B_{p, \omega^*}^i(u, \eta^2 u) - B_{c, \omega^*}^i(u, \eta^2 u) - \langle \llbracket \frac{1}{2} \nu \eta \nabla_h u + \nu u \nabla_h \eta \rrbracket_w, \llbracket (\eta u) \mathbf{n} \rrbracket \rangle_{\mathbb{F}_h^i(\omega^*)} \\ &= B_{p, \omega^*}^i(u, \eta^2 u) - B_{c, \omega^*}^i(u, \eta^2 u) - B_{c, \omega^*}^i(\eta^2 u, u) = B_{\omega^*}^i(u, \eta^2 u). \end{aligned}$$

With the same arguments, we obtain $B_{\omega^*}^\partial(\eta u, \eta u) = B_{\omega^*}^\partial(u, \eta^2 u)$. Since η is supported on $(\omega^*)^-$, the harmonicity of u implies $B_{\omega^*}(u, I_h(\eta^2 u)) = 0$, which we subtract from (9) while plugging in the above identities and using the product rule

to obtain

$$\begin{aligned} B_{\omega^*}(\eta u, \eta u) &= (v u \nabla_h \eta, u \nabla_h \eta)_{\omega^*} + (v \nabla_h u, \nabla_h(\eta^2 u - I_h(\eta^2 u)))_{\omega^*} \\ &\quad + B_{\omega^*}^i(u, \eta^2 u - I_h(\eta^2 u)) + B_{\omega^*}^\partial(u, \eta^2 u - I_h(\eta^2 u)). \end{aligned} \quad (10)$$

We will now show that

$$B_{\omega^*}(\eta u, \eta u) \leq C v_{\max}^{1/2} \|u\|_{L^2(\omega^* \setminus \omega)} \left(\frac{1}{\delta} \|v^{1/2} \nabla_h(\eta u)\|_{L^2(\omega^* \setminus \omega)} + \frac{v_{\max}^{1/2}}{\delta^2} \|u\|_{L^2(\omega^* \setminus \omega)} \right).$$

Once we have this inequality, we can use a weighted Young's inequality to absorb the term involving the gradient of ηu and infer

$$B_{\omega^*}(\eta u, \eta u) \leq \left(C + \frac{C^2}{2\alpha_B(\Omega)} \right) \frac{v_{\max}}{\delta^2} \|u\|_{L^2(\omega^* \setminus \omega)}^2 + \frac{\alpha_B(\Omega)}{2} \|v^{1/2} \nabla_h(\eta u)\|_{L^2(\omega^* \setminus \omega)}^2. \quad (11)$$

Since η is supported on $(\omega^*)^-$, we have $B(\eta u, \eta u) = B_{\omega^*}(\eta u, \eta u)$ and thus $\alpha_B(\Omega) \|\eta u\|_{B^+, \Omega}^2 \leq B_{\omega^*}(\eta u, \eta u)$ due to the coercivity of B . Combining this with (11), the assumptions on η , and noting that the face integrals in the definition of $B_{\omega^*}^+$ are bounded by the face integrals in the definition of B_{Ω}^+ establishes the lemma.

Now, we bound all terms in (10). The first term can be bounded from above by $(v u \nabla_h \eta, u \nabla_h \eta)_{\omega^*} \leq v_{\max} C_\eta^2 \delta^{-2} \|u\|_{L^2(\omega^* \setminus \omega)}^2$. Since $\eta|_{\omega^+} = 1$, we infer that all terms in (10) only have contributions from elements contained in $(\omega^*)^- \setminus \omega^+ \neq \emptyset$. Let $T \in \mathbb{T}_h$ be such an element. Using [3, Lemma 5.4] and an inverse inequality [2, Lemma 1.44], we obtain

$$\begin{aligned} (v \nabla_h u, \nabla_h(\eta^2 u - I_h(\eta^2 u)))_T &\leq v|_T \|\nabla_h u\|_{L^2(T)} \|\nabla_h(\eta^2 u - I_h(\eta^2 u))\|_{L^2(T)} \\ &\lesssim v|_T \|\nabla_h u\|_{L^2(T)} \left(\frac{h_T}{\delta} \|\nabla_h(\eta u)\|_{L^2(T)} + \frac{h_T}{\delta^2} \|u\|_{L^2(T)} \right) \\ &\lesssim v_{\max}^{1/2} \|u\|_{L^2(T)} \left(\frac{1}{\delta} \|v^{1/2} \nabla_h(\eta u)\|_{L^2(T)} + \frac{v_{\max}^{1/2}}{\delta^2} \|u\|_{L^2(T)} \right) \end{aligned}$$

and hence

$$\begin{aligned} (v \nabla_h u, \nabla_h(\eta^2 u - I_h(\eta^2 u)))_{\omega^*} \\ \lesssim v_{\max}^{1/2} \|u\|_{L^2(\omega^* \setminus \omega)} \left(\frac{1}{\delta} \|v^{1/2} \nabla_h(\eta u)\|_{L^2(\omega^* \setminus \omega)} + \frac{v_{\max}^{1/2}}{\delta^2} \|u\|_{L^2(\omega^* \setminus \omega)} \right). \end{aligned} \quad (12)$$

It remains to bound the last two terms of (10). We only consider interior faces since the boundary terms can be treated in the same way. Recall that by definition $B_{\omega^*}^i(u, v) = B_{p, \omega^*}^i(u, v) - B_{c, \omega^*}^i(u, v) - B_{c, \omega^*}^i(v, u)$. Consider two adjacent elements $T_1, T_2 \in \mathbb{T}_h$ with common face $F \in \mathbb{F}_h^i$ and abbreviate $T := T_1 \cup T_2$ and $v_i = v|_{T_i}$. We bound the penalty term B_{p, ω^*}^i face by face:

$$\begin{aligned}
\langle \gamma_h^2 \llbracket \mathbf{u} \mathbf{n} \rrbracket, \llbracket (\eta^2 u - I_h(\eta^2 u)) \mathbf{n} \rrbracket \rangle_F &\lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} h_{T_{\min}}^{-2} \|u\|_{L^2(T)} \|\eta^2 u - I_h(\eta^2 u)\|_{L^2(T)} \\
&\lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} h_{T_{\min}}^{-2} \|u\|_{L^2(T)} \left(\frac{h_{T_{\max}}^2}{\delta} \|\nu^{1/2} \nabla_h(\eta u)\|_{L^2(T)} + \frac{h_{T_{\max}}^2}{\delta^2} \|u\|_{L^2(T)} \right) \\
&\lesssim \nu_{\max}^{1/2} \|u\|_{L^2(T)} \left(\frac{1}{\delta} \|\nu^{1/2} \nabla_h(\eta u)\|_{L^2(T)} + \frac{\nu_{\max}^{1/2}}{\delta^2} \|u\|_{L^2(T)} \right), \tag{13}
\end{aligned}$$

where the first step is carried out analogously to the first step in (5), and we further used [3, Lemma 5.4] as well as [2, Lemma 1.43]. Note that the condition $\eta \in \mathcal{P}_1(\omega^*, \mathbb{T}_h)$ is crucial for the applicability of the discrete trace inequality, since it guarantees that $\eta^2 u$ is piecewise polynomial. Summing over all faces, we obtain the same upper bound for $B_{p, \omega^*}^i(u, \eta^2 u - I_h(\eta^2 u))$ as in (12).

For the first consistency term $B_{c, \omega^*}^i(u, \eta^2 u - I_h(\eta^2 u))$ of $B_{\omega^*}^i$, we again proceed as in (5) to obtain

$$\begin{aligned}
\langle \llbracket \nu \nabla_h u \rrbracket_{\omega}, \llbracket \eta^2 u - I_h(\eta^2 u) \mathbf{n} \rrbracket \rangle_F &\lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} h_{T_{\min}}^{-1} \|\nabla_h u\|_{L^2(T)} \|\eta^2 u - I_h(\eta^2 u)\|_{L^2(T)} \\
&\lesssim \frac{\nu_1 \nu_2}{\nu_1 + \nu_2} h_{T_{\min}}^{-2} \|u\|_{L^2(T)} \|\eta^2 u - I_h(\eta^2 u)\|_{L^2(T)},
\end{aligned}$$

which can then be treated in the same way as (13), such that summing over all faces once again yields the same upper bound for $B_{c, \omega^*}^i(u, \eta^2 u - I_h(\eta^2 u))$ as in (12). The term $B_{c, \omega^*}^i(\eta^2 u - I_h(\eta^2 u), u)$ can be treated analogously. \square

Remark 1 Assuming that ν is piecewise constant is not strictly necessary but leads to smaller constants in Corollary 1 and Lemma 2. For general diffusion coefficients, an additional factor $\sqrt{\nu_{\max}/\nu_{\min}}$ occurs in the estimates, cf. [4, Lemma 3.10].

Lemma 3 (Weak approximation property, [3, Assumption 3.4]) *Let $\omega \subset \omega^* \subset \omega^{**}$ be subdomains of Ω with $\delta := \text{dist}(\omega^*, \partial\omega^{**} \setminus \partial\Omega) > \max_{K \in \mathbb{T}_h: K \cap \omega^* \setminus \omega \neq \emptyset} h_K$, and let $V_\delta(\omega^* \setminus \omega) := \{\mathbf{x} \in \omega^{**} : \text{dist}(\mathbf{x}, \omega^* \setminus \omega) \leq \delta\}$. Then, there exists a constant $C_1 > 0$ depending only on d , such that for each integer $m \geq C_1 |V_\delta(\omega^* \setminus \omega)| \delta^{-d}$ and $h \leq |V_\delta(\omega^* \setminus \omega)|^{1/d} m^{-1/d}$, there exists an m -dimensional space $Q_m(\omega^{**}) \subset L^2(\omega^{**})$ such that for all $u \in \mathcal{H}_B(\omega^{**})$,*

$$\inf_{v \in Q_m(\omega^{**})} \|u - v\|_{L^2(\omega^* \setminus \omega)} \lesssim \nu_{\min}^{-1/2} |V_\delta(\omega^* \setminus \omega)|^{1/d} m^{-1/d} \|u\|_{B^+, \omega^{**}}.$$

Proof. By the assumption on the mesh size, we have $\delta^- := \text{dist}(\omega^*, \partial(\omega^{**})^- \setminus \partial\Omega) > 0$. We define the set $V_{\delta^-}(\omega^* \setminus \omega) := \{\mathbf{x} \in (\omega^{**})^- : \text{dist}(\mathbf{x}, \omega^* \setminus \omega) \leq \delta^-\}$ and denote by $R_h : V_h((\omega^{**})^-) \rightarrow W^{1, \infty}((\omega^{**})^-)$ the reconstruction operator introduced in [1, Section 3] defined on $(\omega^{**})^-$. By [3, Lemma 5.5], there is an m -dimensional space $Y_m \subset L^2((\omega^{**})^-)$ and a constant $C > 0$ depending only on d such that

$$\inf_{v \in Y_m} \|R_h u - v\|_{L^2(\omega^* \setminus \omega)} \leq C |V_{\delta^-}(\omega^* \setminus \omega)|^{1/d} m^{-1/d} \|\nabla_h R_h u\|_{L^2((\omega^{**})^-)}$$

for all $u \in \mathcal{H}((\omega^{**})^-)$. Using the triangle inequality, the previous estimate and [1, Theorem 3.1], we obtain

$$\begin{aligned} \inf_{v \in Y_m} \|u - v\|_{L^2(\omega^* \setminus \omega)} &\leq \|R_h u - u\|_{L^2(\omega^* \setminus \omega)} + \inf_{v \in Y_m} \|R_h u - v\|_{L^2(\omega^* \setminus \omega)} \\ &\lesssim h \|u\|_{B^+, (\omega^{**})^-} + C_1 |\mathbf{V}_{\delta^-}(\omega^* \setminus \omega)|^{1/d} m^{-1/d} \|\nabla_h R_h u\|_{L^2((\omega^{**})^-)} \\ &\lesssim |\mathbf{V}_{\delta^-}(\omega^* \setminus \omega)|^{1/d} m^{-1/d} \nu_{\min}^{-1/2} \|u\|_{B^+, (\omega^{**})^-}. \end{aligned}$$

Defining $Q_m(\omega^{**})$ via extension by zero of functions in Y_m and noting that $|\mathbf{V}_{\delta^-}(\omega^* \setminus \omega)| \leq |\mathbf{V}_{\delta}(\omega^* \setminus \omega)|$, the lemma is established. \square

Having verified all relevant assumptions of [3], we obtain the desired nearly exponential decay of the eigenvalues and the global MS-GFEM error. Note that the Kolmogorov n -widths given in [3, Theorems 3.8 and 2.23] coincide with the eigenvalues stated below due to [3, Lemmas 2.19 and 2.20].

Theorem 1 ([3, Theorem 3.8]) *Assume that $\omega_j \subset \omega_j^*$ are truncated concentric cubes of side length H_j and H_j^* , respectively, that are resolved by the mesh. Let $H_j^* > H_j$. Then, there exist constants $N_j \in \mathbb{N}$, $C_j > 0$ and $c_j > 0$, independent of h , such that for all $n \geq N_j$, if h is sufficiently small, we have*

$$\sqrt{\lambda_{j,n}} \leq C_j e^{-c_j n^{1/d}}.$$

Theorem 2 *The MS-GFEM solution u^G satisfies*

$$\|u^e - u^G\|_{B^+, \Omega} \leq \frac{C_B(\Omega)}{\alpha_B(\Omega)} \sqrt{\kappa \kappa^*} \left(\max_{j=1, \dots, M} \sqrt{\lambda_{j, n_{j+1}}} \frac{C_B(\omega_j^*)}{\alpha_B(\omega_j^*)} \right) \|u^e\|_{B^+, \Omega},$$

where κ and κ^* are the coloring constants of $\{\omega_j\}_{j=1}^M$ and $\{\omega_j^*\}_{j=1}^M$, respectively.

Proof. This follows from combining C ea's Lemma and [3, Theorem 2.8]. The latter is applicable with $\varepsilon_j = \sqrt{\lambda_{j, n_{j+1}}} C_B(\omega_j^*) / \alpha_B(\omega_j^*) \|u^e\|_{B^+, \omega_j^*}$ due to [3, Theorem 2.23], since $\|u^e|_{\omega_j^*} - \psi_j\|_{B^+, \omega_j^*} \leq C_B(\omega_j^*) / \alpha_B(\omega_j^*) \|u^e\|_{B^+, \omega_j^*}$ and $\|\cdot\|_{B^+, \Omega} \leq \|\cdot\|_{\mathcal{H}(\Omega)}$. \square

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